

一般 CDF 方程一种不变性

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摘要 本文给出一般 CDF 方程的一种不变性。据此, 我们可以仅通过积分的方法, 从一般 CDF 方程的已知解得到新的解。本文所得结果概括了文 [3] 的结论。

关键词 CDF 方程 Backlund 变换 MKdV 方程

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MKdV 方程
$$q_t = q_{xxx} + 6q^2 q_x \tag{1}$$

的 Riccati 形式的 Lax 对可化为

$$\begin{aligned} \phi_x &= -(q + \xi \sin 2\phi) \\ \phi_t &= \phi_{xxx} + 2\phi_x^3 + 6\xi \phi_x \sin^2 2\phi \end{aligned} \tag{2}$$

其中 ξ 是一个任意常数^[1], 方程 (2) 称为 CDF (Calogero - Degasperies - Fordy) 方程^[2]. 文 [3] 给出了 CDF 方程的一种不变性。本文讨论一般 CDF 方程

$$\phi_t = \phi_{xxx} + 2\phi_x^3 + 6\phi_x (\xi \sin 2\phi + \eta \cos \phi)^2 \tag{3}$$

其中 ξ 和 η 是两个任意常数, 从一般 CDF 方程的 Backlund 变换出发, 给出一般 CDF 方程的一种不变性。根据这一不变性, 我们可以仅通过积分的方法, 从一般 CDF 方程的已知解得到新的解。

1 一般 CDF 方程的一种不变性

引理 1 一般 CDF 方程 (3) 的 Backlund 变换 (BT) 是

$$\overline{\phi}_x = \phi_x + \xi \sin 2\phi + \eta \cos 2\phi - \xi \sin 2\overline{\phi} - \eta \cos 2\overline{\phi} \tag{4}$$

$$\overline{\phi}_t = \phi_t + R \tag{5}$$

其中

$$\begin{aligned} R = & 2[\phi_{xx} - 2\phi_x(\xi \cos 2\overline{\phi} - \eta \sin 2\overline{\phi})](\xi \cos 2\phi - \eta \sin 2\phi - \xi \cos 2\overline{\phi} + \eta \sin 2\overline{\phi}) \\ & + 2[\phi_x^2 - 2\phi_x(\xi \sin 2\overline{\phi} + \eta \cos 2\overline{\phi}) + (\xi \sin 2\phi + \eta \cos 2\phi)^2 + 2(\xi + \eta)] \\ & (\xi \sin 2\phi + \eta \cos 2\phi - \xi \sin 2\overline{\phi} - \eta \cos 2\overline{\phi}). \end{aligned}$$

证明: 设 ϕ 是一般 CDF 方程 (3) 的一个解, 由 (4) 可得

$$\begin{aligned} \overline{\phi}_{xx} &= \phi_{xx} + 2\phi_x(\xi \cos 2\phi - \eta \sin 2\phi) - 2\overline{\phi}_x(\xi \cos 2\overline{\phi} - \eta \sin 2\overline{\phi}) \\ \overline{\phi}_{xxx} &= \phi_{xxx} + 2\phi_{xx}(\xi \cos 2\phi - \eta \sin 2\phi) - 4\phi_x^2(\xi \sin 2\phi + \eta \cos 2\phi) - 2[\phi_{xx} + \\ & 2\phi_x(\xi \cos 2\phi - \eta \sin 2\phi) - 2\overline{\phi}_x(\xi \cos 2\overline{\phi} - \eta \sin 2\overline{\phi})](\xi \cos 2\overline{\phi} - \eta \sin 2\overline{\phi}) \end{aligned}$$

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$$\begin{aligned} &+ 4(\varnothing_x + \xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})^2(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing}) \\ = &\varnothing_{xxx} + 2\varnothing_{xx}(\xi_{os}2\varnothing - \eta_{in}2\varnothing - \xi_{os}2\overline{\varnothing} + \eta_{in}2\overline{\varnothing}) \\ &- 4\varnothing_x^2(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing}) \\ &8\varnothing_x(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing}) \\ &- 4\varnothing_x(\xi_{os}2\varnothing - \eta_{in}2\varnothing - \xi_{os}2\overline{\varnothing} + \eta_{in}2\overline{\varnothing})(\xi_{os}2\overline{\varnothing} - \eta_{in}2\overline{\varnothing}) \\ &+ 4(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})(\xi_{os}2\overline{\varnothing} - \eta_{in}2\overline{\varnothing})^2 \\ &+ 4(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})^2(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing}). \end{aligned}$$

$$\begin{aligned} &\text{和} 2\overline{\varnothing}_x^3 + 6\overline{\varnothing}_x(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing})^2 \\ = &2\overline{\varnothing}_x^3 + 6\overline{\varnothing}_x(\xi_{in}2\varnothing + \eta_{os}2\varnothing)^2 + 6\overline{\varnothing}_x^2(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing}) \\ &- 12\varnothing_x(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing}) \\ &+ 6(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing})^2 \\ &+ 2(\xi_{in}2\varnothing + \eta_{os}2\varnothing - \xi_{in}2\overline{\varnothing} - \eta_{os}2\overline{\varnothing})^3. \end{aligned}$$

那么

$$\begin{aligned} &\overline{\varnothing}_{xxx} + 2\overline{\varnothing}_x^3 + 6\overline{\varnothing}_x(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing})^2 \\ = &\varnothing_{xxx} + 2\varnothing_x^3 + 6\varnothing_x(\xi_{in}2\varnothing + \eta_{os}2\overline{\varnothing})^2 + R \\ = &\varnothing_t + R. \end{aligned}$$

因此，由 (5) 可得 $\overline{\varnothing}_{xxx} + 2\overline{\varnothing}_x^3 + 6\overline{\varnothing}_x(\xi_{in}2\overline{\varnothing} + \eta_{os}2\overline{\varnothing})^2 = \overline{\varnothing}$

另一方面，如果 $\overline{\varnothing}$ 是一般 CDF 方程 (3) 的一个解，那么 \varnothing 也是一个解。

因此，按照 Backlund 变换 (BT) 的定义 (参看 [4, p. 154])，关系式 (4) 和 (5) 是一般 CDF 方程的一个 BT. 引理证毕。

按照 BT 纲领，如果已知某非线性微分方程的一个解，我们可以利用 BT 关系找出该微分方程的新解。

在下面，我们用 $\int dx$ 表示 f 的任意取定的一个原函数。

引理 2 如果 \varnothing 是一般 CDF 方程 (3) 的一个解，那么

$$\begin{aligned} C \equiv & -\frac{1}{2} \left[\int (\xi_{os}2\varnothing - \eta_{in}2\varnothing) dx \right]_t - \varnothing_{xx}(\xi_{in}2\varnothing + \eta_{os}2\varnothing) + \varnothing_x^2(\xi_{os}2\varnothing - \eta_{in}2\varnothing) \\ & [(\xi_{in}2\varnothing + \eta_{os}2\varnothing)^2 + 2(\xi + \eta)](\xi_{os}2\varnothing - \eta_{in}2\varnothing) \end{aligned}$$

和

$$\begin{aligned} h \equiv & -2 \left[\int (\xi_{in}2\varnothing + \eta_{os}2\varnothing) e^{-2 \int (\xi_{os}2\varnothing - \eta_{in}2\varnothing) dx} dx \right]_t \\ & + 8c \int (\xi_{in}2\varnothing + \eta_{os}2\varnothing) e^{-2 \int (\xi_{os}2\varnothing - \eta_{in}2\varnothing) dx} dx \\ & + 4[\varnothing_{xx} + 2\varnothing_x(\xi_{os}2\varnothing - \eta_{in}2\varnothing)](\xi_{os}2\varnothing - \eta_{in}2\varnothing) e^{-2 \int (\xi_{os}2\varnothing - \eta_{in}2\varnothing) dx} \\ & + 4[\varnothing_x^2 + 2\varnothing_x(\xi_{in}2\varnothing + \eta_{os}2\varnothing) + (\xi_{in}2\varnothing + \eta_{os}2\varnothing)^2 \\ & + 2(\xi + \eta)](\xi_{in}2\varnothing + \eta_{os}2\varnothing) e^{-2 \int (\xi_{os}2\varnothing - \eta_{in}2\varnothing) dx} \end{aligned}$$

是仅含 t 的函数 (即, $c_x = h_x = 0$).

证明：如果 \varnothing 是一般 CDF 方程 (3) 的一个解，那么

$$C_x=(\xi_{in}2\varnothing+\eta_{os}2\varnothing)[\varnothing_t-\varnothing_{xxx}-2\varnothing_x^3-6\varnothing_x(\xi_{in}2\varnothing+\eta_{os}2\varnothing)^2]=0,$$
$$h_x=(\xi_{os}2\varnothing-\eta_{in}2\varnothing)[\varnothing_{xxx}+2\varnothing_x^3+6\varnothing_x(\xi_{in}2\varnothing+\eta_{os}2\varnothing)^2-\varnothing_t]e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}$$
$$+8(\xi_{in}2\varnothing+\eta_{os}2\varnothing)[c+\frac{1}{2}(\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx)_t+\varnothing_{xx}(\xi_{in}2\varnothing$$
$$+\eta_{os}2\varnothing)-\varnothing_x^2(\xi_{os}2\varnothing-\eta_{in}2\varnothing)-((\xi_{in}2\varnothing+\eta_{os}2\varnothing)^2+2(\xi$$
$$+\eta))(\xi_{os}2\varnothing-\eta_{in}2\varnothing)]e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}=0。$$

引理证毕。

定理 3 如果 \varnothing 是一般 CDF 方程 (3) 的一个解，那么

$$\overline{\varnothing}=\arctan(\tan\varnothing+Y) \tag{6}$$

也是 (3) 的一个解，其中

$$Y=\sec^2\varnothing e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}/Q \tag{7}$$

$$Q=-\tan\varnothing e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}$$
$$-2\int(\xi_{in}2\varnothing+\eta_{os}2\varnothing)e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}dx+\varepsilon \tag{8}$$

$$\varepsilon=e^{4\int h(t)dt}(\alpha-\int h(t)e^{-4\int h(t)dt}dt) \tag{9}$$

α 是一个任意常数。(即， $\varepsilon'=4c(t)-h(t)$)

证明：我们直接验证 \varnothing 和 $\overline{\varnothing}$ 满足 BT 关系 (4) 和 (5)。

由 (6)，(7) 和 (8)，我们有

$$\overline{\varnothing}_x\sec^2\overline{\varnothing}=\varnothing_x\sec^2\varnothing+Y_x,$$
$$Y_x=2[\tan\varnothing(\varnothing_x+\xi_{in}2\varnothing+\eta_{os}2\varnothing+\eta-\xi)Y$$
$$+(\varnothing_x+\xi_{in}2\varnothing+\eta_{os}2\varnothing+\eta)Y^2,$$
$$\sec^2\overline{\varnothing}(\overline{\varnothing}_x+\xi_{in}2\overline{\varnothing}+\eta_{os}2\overline{\varnothing})=\sec^2\varnothing(\varnothing_x+\xi_{in}2\varnothing+\eta_{os}2\varnothing)。$$

因此，(4) 式成立，下面，我们仅需证明 (5) 式成立。

由于

$$\overline{\varnothing}_t=\varnothing_t\sec^2\varnothing/\sec^2\overline{\varnothing}+Y_t/\sec^2\overline{\varnothing}$$
$$\sec^2\overline{\varnothing}=1+(\tan\varnothing+Y)^2=\sec^2\varnothing+2Y\tan\varnothing+Y^2,$$

(5) 成立的充分必要条件是

$$-(2Y\tan\varnothing+Y^2)\varnothing_t+Y_t=R\sec^2\overline{\varnothing}。 \tag{10}$$

由 (6)，(7) 和 (8)，

$$Y_t=2Y\varnothing_t\tan\varnothing-2Y[\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx]_t-YQ_t/Q,$$
$$Q_t=[-\varnothing_t\sec^2\varnothing+2\tan\varnothing(\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx)_t]e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}$$
$$-2[\int(\xi_{in}2\varnothing+\eta_{os}2\varnothing)e^{-2\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx}dx]_t+\varepsilon'，$$

我们有

$$Y_t=\varnothing_t(2Y\tan\varnothing+Y^2)-2Y(\int(\xi_{os}2\varnothing-\eta_{in}2\varnothing)dx)_t$$

$$-Y^2 \sin 2\varnothing (\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx)_t + 2Y [\int \xi_{in} 2\varnothing + \eta_{os} 2\varnothing) e^{-2 \int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx} dx]_t / Q - Y \epsilon' / Q.$$

那么 (10) 化为

$$\begin{aligned} & -2Y [\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx]_t - Y^2 \sin 2\varnothing (\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx)_t \\ & + 2Y [\int \xi_{in} 2\varnothing + \eta_{os} 2\varnothing) e^{-2 \int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx} dx]_t / Q - Y \epsilon' / Q \\ & = R \sec^2 \varnothing \end{aligned} \quad (11)$$

将

$$\begin{aligned} \cos 2\varnothing - \cos 2\overline{\varnothing} &= 2Y (2 \tan \varnothing + Y) / \sec^2 \varnothing \sec^2 \overline{\varnothing}, \\ \sin 2\varnothing - \sin 2\overline{\varnothing} &= 2Y (\tan^2 \varnothing + Y \tan \varnothing - 1) / \sec^2 \varnothing \sec^2 \overline{\varnothing} \end{aligned}$$

代入 R 的表达式, (11) 化为

$$\begin{aligned} & -2 [\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx]_t - Y \sin 2\varnothing (\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx)_t \\ & + 2 [\int \xi_{in} 2\varnothing + \eta_{os} 2\varnothing) e^{-2 \int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx} dx]_t / Q - \epsilon' / Q \\ & = 4 \cos^2 \varnothing [(\varnothing_{xx} + 2\varnothing_x (\xi_{os} 2\varnothing - \eta_{in} 2\varnothing)) (\xi 2 \tan \varnothing + Y) - \eta \tan^2 \varnothing + Y \tan \varnothing - 1) + (\varnothing_x^2 + 2\varnothing_x (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing) + (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing)^2 + 2(\xi + \eta)) \xi \tan^2 \varnothing + Y \tan \varnothing - 1) + \eta 2 \tan \varnothing + Y)]. \end{aligned} \quad (12)$$

由于

$$\begin{aligned} & -2 [\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx]_t - 4 \cos^2 \varnothing [\varnothing_{xx} + 2\varnothing_x (\xi_{os} 2\varnothing - \eta_{in} 2\varnothing)] [2 \xi \tan \varnothing - \eta \tan^2 \varnothing - 1] - 4 \cos^2 \varnothing [\varnothing_x^2 + 2\varnothing_x (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing) + (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing)^2 + 2(\xi + \eta)] [\xi \tan^2 \varnothing - 1) + 2 \eta \tan \varnothing] \\ & = 4c(t), \\ & -\sin 2\varnothing [\int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx]_t - 4 \cos^2 \varnothing [\varnothing_{xx} + 2\varnothing_x (\xi_{os} 2\varnothing - \eta_{in} 2\varnothing)] [\xi - \eta \tan \varnothing] - 4 \cos^2 \varnothing [\varnothing_x^2 + 2\varnothing_x (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing) + (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing)^2 + 2(\xi + \eta)] [\xi \tan \varnothing + \eta] \\ & = H \cos^2 \varnothing, \end{aligned}$$

其中

$$\begin{aligned} H &= -4 [\varnothing_{xx} + 2\varnothing_x (\xi_{os} 2\varnothing - \eta_{in} 2\varnothing)] (\xi_{os} 2\varnothing - \eta_{in} 2\varnothing) \\ & - 4 [\varnothing_x^2 + 2\varnothing_x (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing) + (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing)^2 + 2(\xi + \eta)] (\xi_{in} 2\varnothing + \eta_{os} 2\varnothing) + 4c(t) \tan \varnothing. \end{aligned}$$

因此, (12) 化为

$$\begin{aligned} & 4c(t) + H e^{-2 \int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx} / Q \\ & + 2 [\int \xi_{in} 2\varnothing + \eta_{os} 2\varnothing) e^{-2 \int \xi_{os} 2\varnothing - \eta_{in} 2\varnothing) dx} dx]_t / Q - \epsilon' / Q = 0. \end{aligned} \quad (13)$$

将 (8) 代入 (13) , 我们有

$$\begin{aligned} &4c(t) \, \varepsilon - \varepsilon' + (H - 4c(t) \tan \varnothing) e^{-2 \int \xi \cos 2 \varnothing - \eta \sin 2 \varnothing \, dx} \\ &- 8c(t) \int \xi \sin 2 \varnothing + \eta \cos 2 \varnothing \, e^{-2 \int \xi \cos 2 \varnothing - \eta \sin 2 \varnothing \, dx} dx \\ &+ 2 \Big[\int \xi \sin 2 \varnothing + \eta \cos 2 \varnothing \, e^{-2 \int \xi \cos 2 \varnothing - \eta \sin 2 \varnothing \, dx} dx \Big]_t = 0. \end{aligned}$$

即, $\varepsilon' = 4c(t) \, \varepsilon - h(t)$. 定理证毕.

II MKdV 方程的新解

在方程 (1) 和 (3) 之间存在一个变换

$$q = - (\varnothing_x + \xi \sin 2 \varnothing + \eta \cos 2 \varnothing) \tag{14}$$

事实上, 将 (14) 代入 (1) , 我们有

$$\begin{aligned} &q_t - (q_{xxx} + 6q^2 q_x) \\ &= - (D_x + 2 \xi \cos 2 \varnothing - 2 \eta \sin 2 \varnothing) (\varnothing_t - \varnothing_{xxx} - 2 \varnothing_x^3 - 6 \varnothing_x (\xi \sin 2 \varnothing + \eta \cos 2 \varnothing)^2) . \end{aligned}$$

由于当我们将 (\varnothing , ξ η) 变为 ($-\varnothing$, $-\xi$ η) 时, 方程 (3) 是不变的, 因此在方程 (1) 和 (3) 之间存在另一个变换

$$q = \varnothing_x - \xi \sin 2 \varnothing - \eta \cos 2 \varnothing \tag{15}$$

按照定理 3, 我们可以由一般 CDF 方程的已知解得到新解. 那么, 由 (14) 和 (15) , 我们可以得到 MKdV 方程 (1) 的对应新解

$$\begin{aligned} q_1 &= \pm (\overline{\varnothing}_x + \xi \sin 2 \overline{\varnothing} + \eta \cos 2 \overline{\varnothing}) , \\ q_2 &= \pm (\overline{\varnothing}_x - \xi \sin 2 \overline{\varnothing} - \eta \cos 2 \overline{\varnothing}) , \end{aligned}$$

在 $\xi = 0$ 的情况, 我们可以得到 MKdV 方程 (1) 的一组单参数新解

例 1 我们取定方程 (3) 的平凡解 $\varnothing = 0$ 和

$$\int \sin 2 \varnothing \, dx = 0, \int \cos 2 \varnothing e^{2 \eta \int \sin 2 \varnothing \, dx} \, dx = x .$$

那么 $c = 0$, $h = 12 \eta$, $\varepsilon = -12 \eta t$, $Q = \alpha - 2 \eta - 12 \eta t$, $Y = 1/Q$ (α 是一个任意常数) , 我们得到方程 (3) 的解 $\overline{\varnothing} = \arctan Y$ 和 MKdV 方程 (1) 的对应解:

$$\begin{aligned} q_1 &= \pm (\overline{\varnothing}_x + \eta \cos 2 \overline{\varnothing}) = \pm \eta \\ q_2 &= \pm (\overline{\varnothing}_x - \eta \cos 2 \overline{\varnothing}) = \pm \eta (3 - Q^2) / (1 + Q^2) . \end{aligned}$$

例 2 我们考虑方程 (3) 的平凡解 $\varnothing = \pi/4$, 并取定

$$\int \cos 2 \varnothing \, dx = 0, \int \sin 2 \varnothing e^{-2 \xi \int \cos 2 \varnothing \, dx} \, dx = x .$$

那么 $c = 0$, $h = -12 \xi$. 我们得到方程 (3) 的解 $\overline{\varnothing} = \arctan (1 - \frac{1}{\omega})$ ($\omega = \xi + 6 \xi t + \delta$ δ 是一个任意常数) 和 MKdV 方程 (1) 的对应解:

$$\begin{aligned} q_1 &= \pm (\overline{\varnothing}_x + \xi \sin 2 \overline{\varnothing}) = \pm \xi \\ q_2 &= \pm (\overline{\varnothing}_x - \xi \sin 2 \overline{\varnothing}) = \pm (1 - \frac{1}{H}) , \\ (H &= \omega^2 - \omega + \frac{1}{2}) . \end{aligned}$$

在 $\xi \neq 0$ 和 $\eta \neq 0$ 的情况, 我们可以得到 MKdV 方程 (1) 的一组双参数新解.

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Relationship Between Retention And
HomologousSeauence Number of Long Chain
Alcohol Acid And Ester in Rplc

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Abstract Based on molecular structure and Jiang Mingaian ´ organic compound ho-
mologous linear rule, the quantitative relationship between reten tion and the homologous
sequ en ce number is identified for long Chain alcohool, acid and ester in reversed -phase
high -performanceliquig Chromatography (RPLLC) and is supported by experimental da-
ta. The result is Satisfactory.

Keywords Reversed -phase liquid Chromatography (RPLC) Retention Homolo-
gous Sequence number.
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A Constant Property of general CDF equation

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Abstract In this paper. We give a constant property of general CDF equation. Ac-
cording to it, We may get a new Solution from known Solution of a general CDF equation,
only using integral method.

Keywords CDF equation Backlund transform Mkdv equation